Amendments to the Claims:

This listing of claims will replace all prior versions, and listings, of claims in the application:

Listing of Claims:

1.-8. (canceled)

9. (previously presented) A method for applying tire reinforcement sections to a support using a machine for manufacturing the tire reinforcement sections, the machine including a guide for guiding a reinforcement cord along a longitudinal direction of the reinforcement cord to a cutoff point, a cutting device for cutting the reinforcement cord at the cutoff point at a predetermined cutting interval to form the tire reinforcement sections, the cutting device comprising a knife-supporting disk, a knife mounted on the knife-supporting disk, and a motor driving an input shaft, wherein the knife-supporting disk is coupled to the input shaft by a drive connection, the method comprising the steps of:

feeding the reinforcement cord through the guide to the cutoff point;

driving the input shaft by the motor at a selected input shaft rotational speed;

rotating and moving the knife-supporting disk by the drive connection in response to only the driving of the input shaft such that knife speed and the cutting interval are both controlled only by said selected input shaft rotational speed, and the knife moves along a closed path which passes proximate the cutoff point but passes through the cutoff point only every n passes of the knife proximate the cutoff point, wherein n is greater than or equal to two, the reinforcement cord being cut to form the tire reinforcement sections when the knife passes through the cutoff point; and

depositing the cut tire reinforcement section onto the support.

10. (previously presented) The method of claim 9, wherein said step of rotating the knife- supporting disk comprises rotating the knife-supporting disk such that the rotational speed of the knife-supporting disk is greater than the selected input shaft rotational speed.

11. (previously presented) The method of claim 10, wherein said step of rotating the knife- supporting disk comprises rotating the knife-supporting disk such that the rotational speed of the knife-supporting disk is at least two times greater than the input shaft rotational speed.

12. (previously presented) The method of claim 9, wherein said closed path lies within a plane.

13. (previously presented) The method of claim 9, wherein the knife is held at a fixed position on the knife-supporting disk.

14. (currently amended) The method of claim 9, wherein said step of depositing comprises applying the cut tire reinforcement section to a point of contact on the support by an application roller bearing against the support, the application roller ~~bearing~~ being driven by a movement of the support, wherein a distance between the point of contact and the cutoff point is not greater than a length of the cut tire reinforcement.

15. (previously presented) The method of claim 9, wherein the drive connection comprises a planet gear assembly including a planet carrier connected to the input shaft, a planet gear rotatably coupled to the planet carrier for rotating about an axis of rotation parallel to the input shaft and at a distance therefrom, and a fixed toothed wheel, and wherein said step of driving the input shaft comprises driving the planet carrier.

16. (previously presented) The method of claim 15, wherein the knife-supporting disk is coupled to the planet gear for rotation therewith about a common axis, the planet gear being engaged with the fixed toothed wheel, said step of rotating the knife-supporting disk comprising rotating the planet gear about the axis of rotation when the planet carrier is rotated by rolling of the planet gear on the fixed toothed wheel.

17. (currently amended) The method of claim 16, wherein said step of rotating and moving the knife-supporting disk further comprises operating the drive connection with a gear ratio between the number of teeth on the planet gear and the number of teeth on the toothed gear such that the knife passes through the cutoff point only every said n passes of the knife proximate the cutoff point during each revolution ~~revolutions~~ of the planet carrier.

18. (currently amended) The method of claim 9, further comprising the step of moving the knife-supporting disk toward the cutoff point only every said n passes of the knife proximate the cutoff point.

19. (previously presented) The method of claim 18, wherein the input shaft is movable with the knife-supporting disk toward the cutoff point, and the drive connection comprises a cam connected to the input shaft, and wherein said step of moving the knife-supporting disk comprises moving the knife-supporting disk and the input shaft in response to the interaction during rotation of the input shaft between the cam and a fixed element.